

On the compatible mappings in Sb-Menger space with application

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Abstract—In this paper, we introduce the concept of various mappings like compatible mappings, weakly compatible mappings, semi-compatible mappings, and mappings satisfying the property (E.A.) with example. As an application of weak compatible maps and E.A property we proved a fixed-point theorem which generalize the result of Aalam et al. [2] in the new structure of Sb-Menger spaces. We have also given examples of our results.

Index Terms—S-Menger Space, Sb-Menger space, Fixed Point, Compatible Maps, Weak

MSC—47H10, 54H25.

I. Introduction

Recently Sarkar et.al [9] introduce S-Menger space, very recently Keer et.al [6-8] introduce the S_b -Menger space which is the generalization of S and b metric space.

On the other hand, the various types of compatible maps play a very important role in fixed point theory. The notion of compatible mappings was introduced by Gerald Jungck [4] in (1986). The definition of semi-compatible mappings was defined by Y. J. Cho, B. K. Sharma and S. S. Sahu [3] in (1995). The concept of weakly compatible mappings was given by Gerald Jungck [5] in (1996) and the concept of property (E.A.) was introduced by Aamri and El Moutawakil [1] in [2002].

By inspiring above work, we investigate various types of compatible maps, weak compatible maps, semi-compatible maps and the property (E.A) in the structure of S_b -Menger space. Our results extend and generalize the result of Alam et.al [2] in S_b -Menger space.

II. Preliminaries

We recall the following definitions.

Definition 2.1.[10] A map $*$: $X^3 \rightarrow X$ is called continuous t-norm if it satisfies the following conditions:

1. $*(a, 1, 1) = a$, $*(0, 0, 0) = 0$;
2. $*(a, b, c) = *(a, c, b) = *(b, c, a)$;
3. $*(a_1, b_1, c_1) \geq *(a_2, b_2, c_2)$ for $a_1 \geq a_2, b_1 \geq b_2, c_1 \geq c_2$.

Examples of t -norm are

$$1: x * y * z = x.y.z \text{ and}$$

$$2: x * y * z = \min \{x.y.z\} \text{ minimum } t \text{ -norm}$$

Definition 2.2. ([9] S -Menger space)

The 3-tuple $(X, S, *)$ is said to be S -Menger space if X is a non-empty set, S is a function defined on X^3 to the set of distribution function and $*$ is a continuous third order t -norm such that the following conditions are satisfied:

1. $S_{(x,y,z)}(0) = 0$ for all $x, y, z \in X$
2. $S_{(x,x,y)}(t) < 1$ for $t > 0$ with $x \neq y$,
3. $S_{(x,y,z)}(t) = 1$ for all $t > 0$, if and only if $x = y = z$,
4. $S_{(x,y,z)}(t) \geq * (S_{(x,x,a)}(t_1), S_{(y,y,a)}(t_2), S_{(z,z,a)}(t_3))$,
where $t = t_1 + t_2 + t_3$ and $t, t_1, t_2, t_3 > 0$ for all $x, y, z, a \in X$

Definition 2.3.[6] (S_b -Menger space): The quadruple $(X, S_b, *, k)$ is said to be S_b -Menger space if X be a nonempty set, and $k \geq 1$ be a given real number, S_b is a distribution function on X^3 and $*$ is a continuous third order t -norm such that the following conditions are satisfied:

1. $S_{b(x,y,z)}(0) = 0$ for all $x, y, z \in X$
2. $S_{b(x,x,y)}(t) < 1$ for $t > 0$ with $x \neq y$,
3. $S_{b(x,y,z)}(t) = 1$ for all $t > 0$, if and only if $x = y = z$,
4. $S_{b(x,y,z)}(kt) \geq [* (S_{b(x,x,a)}(t_1), S_{b(y,y,a)}(t_2), S_{b(z,z,a)}(t_3))]$,
where $t = t_1 + t_2 + t_3$ and $t, t_1, t_2, t_3 > 0$ for all $x, y, z, a \in X$

Definition 2.4. [6] The S_b - Menger space is called symmetric if $S_{b(x,x,y)}(t) = S_{b(y,y,x)}(t)$

Definition 2.5. [6] Let $(X, S_b, *, k)$ be a symmetric S_b - Menger space then a sequence $\{x_n\} \in X$ is said to be convergent to a point $x \in X$ if $S_{b(x_n, x_n, x)}(t) = 1$ for all $t > 0$.

Definition 2.6. [6] Let $(X, S_b, *, k)$ be a symmetric S_b - Menger space then a sequence $\{x_n\} \in X$ is called Cauchy sequence if $x \in X$ if $S_{b(x_n, x_n, x_{n+s})}(t) = 1$ for all $t, s > 0$.

Lemma 2.7.[6] Let $(X, S_b, *, k)$ be an S_b -Menger space with continuous third order t -norm. Then $S_{b(x,x,y)}(t)$ is non-decreasing with respect to t , for all $x, y \in X$

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III. Main Results

Definition 3.1. Let S and T maps from an S_b -Menger space $(X, S_b, *, k)$ into itself. The maps S and T are said to be compatible, if for all $t > 0$.

$$S_{b(STx_n, STx_n, TSx_n)}(t) = 1$$

whenever $\{x_n\}$ is a sequence in X such that $Sx_n = Tx_n = z$ for some $z \in X$.

Example 3.2. Let $X = [2, 20)$. For each $t \in (0, \infty)$ and for all $x, y, z \in X$, define

$$S_{b(x,y,z)}(t) = \begin{cases} 0, & t = 0 \\ \frac{t}{t+[|x-z|+|y-z|]^2}, & t \geq 0 \end{cases}$$

Clearly $(X, S_b, *, k)$ is an S_b -Menger space, where $*$ is defined by $a * b * c = abc$.

Let g and f be self-maps of X defined as

$$S(x) = \begin{cases} 2, & \text{if } x = 2 \text{ or } x > 5 \\ 6, & \text{if } 2 < x \leq 5 \end{cases} \quad T(x) = \begin{cases} 2 & \text{if } x = 2 \text{ or } x > 5 \\ 12 & \text{if } 2 < x \leq 5 \end{cases}$$

Let sequence $\{x_n\}$ be defined as $x_n = 5 + \frac{1}{n}$, $n \geq 1$ then we have

$$Sx_n = \lim_{n \rightarrow \infty} Tx_n = 2.$$

$$\text{Hence, } S \text{ and } T \text{ satisfy the property (E.A.). Also, } \lim_{n \rightarrow \infty} S_{b(STx_n, STx_n, TSx_n)}(t) = \frac{t}{t+[|2-2|+|2-2|]^2} = \frac{t}{t+0} = 1$$

This shows that T and f are compatible.

Definition 3.3. Let S and T be maps from an S_b -Menger space space $(X, S_b, *, k)$ into itself. The maps are said to be weakly compatible, if they commute at their coincidence points, that is, $Sz = Tz$ implies that $STz = TSz$.

Definition 3.4. Let S and T maps from an S_b -Menger space $(X, S_b, *, k)$ into itself. The maps S and T are said to be semi-compatible, if for all $t > 0$.

$$S_{b(STx_n, STx_n, TSz)}(t) = 1$$

whenever $\{x_n\}$ is a sequence in X such that $gx_n = fx_n = z$ for some $z \in X$.

Note that the semi-compatibility of the pair (S, T) , need not imply the semi-compatibility of (T, S) .

The following is an example of a pair of self-maps (S, T) which is compatible but not semi-compatible. Further, it is also seen that the semi-compatibility of the pair (S, T) need not imply the semi-compatibility of (T, S) .

Example 3.5. Let $X = [0, 1]$ and let $(X, S_b, *, k)$ be the S_b -Menger space with

$$S_{b(x,y,z)}(t) = \begin{cases} e^{\left[\frac{|x-z|+|y-z|}{t}\right]^{-1}}, & t > 0 \\ 0 & t = 0 \end{cases} \text{ for all } x, y, z \in X, t > 0.$$

Example 3.6. Define self-maps S as follow:

$$S(x) = \begin{cases} x, & \text{when } 0 \leq x < \frac{1}{2} \\ 1, & \text{when } x \geq \frac{1}{2} \end{cases}$$

Let I be the identity map on X and $x_n = \frac{1}{2} - \frac{1}{n}$. Then, $\{Ix_n\} = \{x_n\} \rightarrow \frac{1}{2}$ and $\{Sx_n\} = \{x_n\} \rightarrow \frac{1}{2}$. Thus, $\{ISx_n\} = \{Sx_n\} = \frac{1}{2} \neq S\{\frac{1}{2}\}$.

Hence (IS) is not semi-compatible.

Again as (I, S) is commuting, it is compatible. Further, for any sequence $\{x_n\}$ in X such that $\{x_n\} \rightarrow x$ and $\{Sx_n\} \rightarrow x$, we have $\{SIx_n\} = \{Sx_n\} \rightarrow x = Ix$. Hence (SI) is always semi-compatible

Example 3.7. Let $X = [0, 2]$ and $(X, S_b, *)$ be an S_b -Menger space, where the definition of $*$ and S_b are same as defined in example 3.3. Define self-maps A and G on X as follows.

$$A(x) = \begin{cases} 2, & \text{if } 0 \leq x \leq 1 \\ \frac{x}{2}, & \text{if } 1 < x \leq 2 \end{cases} \quad G(x) = \begin{cases} 2, & \text{if } x = 1 \\ \frac{x+3}{5}, & \text{otherwise} \end{cases}$$

and $x_n = 2 - \frac{1}{2n}$, $n \geq 1$. Then we have $G(1) = A(1) = 2$ and $G(2) = A(2) = 1$. Also $GA(1) = AG(1) = 1$ and $GA(2) = AG(2) = 2$. Thus (A, G) is weak compatible. Again $Ax_n = 1 - \frac{1}{4n}$, $Gx_n = 1 - \frac{1}{10n}$.

Thus $Ax_n \rightarrow 1$, $Gx_n \rightarrow 1$.

Hence $u = 1$.

Further, $GAx_n = \frac{4}{5} - \frac{1}{20n}$, $AGx_n = 2$.

Now $S_{b(AGx_n, AGx_n, Gu)}(t) = S_{b(2, 2, 2)}(t) = 1$

$$\begin{aligned} S_{b(AGx_n, AGx_n, GAx_n)}(t) &= S_{b(2, 2, \frac{4}{5} - \frac{1}{20n})}(t) \\ &= \frac{t}{t + [|2 - \frac{4}{5}| + |2 - \frac{4}{5}|]^2} \\ &= \frac{t}{t + [\frac{12}{5}]^2} < 1 \quad \forall t > 0. \end{aligned}$$

Hence (A, G) is semi-compatible but it is not compatible.

Remark 3.8. The above example gives an important aspect of semi-compatibility as the pair of self-maps (IS) is commuting; hence it is weakly commuting, compatible and weak compatible yet it is not semi-compatible. Further, it is to be noted that the pair (S, I) is semi-compatible but (I, S) is not semi-compatible here. The following is an example of a pair of self-maps (A, S) which is semi-compatible but not compatible.

Definition 3.9. Let S and T be two self-maps of an S_b -Menger space $(X, S_b, *, k)$. We say that S and T satisfy the property (E.A.) if there exists a sequence $\{x_n\}$ such that $Sx_n = Tx_n = z$ for some $z \in X$.

Remark 3.10. Note that the weakly compatible and property (E.A.) are independent to each other. See the following example

Example 3.11. Let $(X, S_b, *, k)$ be an S_b -Menger space where $X = [0, 1]$ and S_b is defined as in 3.3. Defined $g, f: X \rightarrow X$ by

$$g(x) = 1 - x, \text{ if } x \in [0, \frac{1}{2}] \text{ and } g(x) = 0, \text{ if } x \in (\frac{1}{2}, 1]$$

$$f(x) = \frac{1}{2}, \text{ if } x \in [0, \frac{1}{2}] \text{ and } f(x) = \frac{3}{4}, \text{ if } x \in (\frac{1}{2}, 1]$$

Then, for the sequence $\{x_n\} = \{\frac{1}{2} - \frac{1}{n}\}$, $n \geq 2$. we have

$$g\left(\frac{1}{2} - \frac{1}{n}\right) = \left(\frac{1}{2} + \frac{1}{n}\right) = \frac{1}{2} = f\left(\frac{1}{2} - \frac{1}{n}\right)$$

Thus, the pair (g, f) satisfies property (E.A). Further, g and f are weakly compatible since $x = \frac{1}{2}$ is their unique coincidence point and $gf\left(\frac{1}{2}\right) = g\left(\frac{1}{2}\right) = f\left(\frac{1}{2}\right) = fg\left(\frac{1}{2}\right)$. We further observe that

$$S_b\left(gf\left(\frac{1}{2} - \frac{1}{n}\right), gf\left(\frac{1}{2} - \frac{1}{n}\right), fg\left(\frac{1}{2} - \frac{1}{n}\right)\right) = \frac{t}{t + [2\left|gf\left(\frac{1}{2} - \frac{1}{n}\right) - fg\left(\frac{1}{2} - \frac{1}{n}\right)\right|]^2}$$

$$= \frac{t}{t + [2\left|\frac{1}{2} - \frac{3}{4}\right|]^2} = \frac{t}{t + [\frac{1}{2}]^2} \neq 1$$

showing that the pair (g, f) is noncompatible.

A Class of Implicit Relation: Let ϕ be the set of all real continuous functions $\phi : [R^+]^4 \rightarrow R$, nondecreasing in first argument and satisfying the following conditions.

- ¹ For $u, v \geq 0$, $\phi(u, v, v, u) \geq 0$ or $\phi(u, v, u, v) \geq 0$ implies $u \geq v$ (a)
- ² $\phi(u, v, 1, 1) \geq 0$ implies that $u \geq 1$ (b)

Application of compatible maps and (E.A) property: As an application of weak compatible maps and the property (EA), we prove the fixed-point theorem of Alam et.al [2] in S_b -Menger space.

Theorem 3.12: Let L, M, N and O be self-maps of an S_b –Menger space $(X, S_b, *, k)$ satisfying the following conditions:

$$L(X) \subseteq O(X), M(X) \subseteq N(X); \dots\dots\dots (3.12.1)$$

$$(L, N) \text{ and } (M, O) \text{ are weakly compatible pairs } \dots\dots\dots (3.12.2)$$

$$(L, N) \text{ or } (M, O) \text{ satisfies the property (E.A) ; } \dots\dots\dots (3.12.3)$$

For some $\phi \in \Phi$, there exist $k \in (0, 1)$ such that for all $x, y \in X, t > 0$

$$\phi(S_{b(Lx, Lx, My)}(kt), S_{b(Nx, Nx, Oy)}(t), S_{b(Lx, Lx, Nx)}(t), S_{b(Ly, Ly, Oy)}(t)) \geq 0 \dots\dots (3.12.4)$$

If the range of one of the maps L, M, N or O is a complete subspace of X , then L, M, N and O have a unique common fixed point in X .

Proof: If the pair (M, O) satisfies the property (E.A) then there exist a sequence $\{x_n\}$ such that $Mx_n \rightarrow z$ and $Ox_n \rightarrow z$ for some $z \in X$ as $n \rightarrow \infty$.

Since $M(X) \subseteq N(X)$, there exist in X a sequence $\{y_n\}$ such that $Mx_n \subseteq Nx_n$.

Hence $Ny_n \rightarrow z$ as $n \rightarrow \infty$.

Now we claim that $Ly_n \rightarrow z$ as $n \rightarrow \infty$. Suppose $Ly_n \rightarrow w (\neq z) \in X$, then by (3.12.4),

we have

$$\phi(S_{b(Ly_n, Ly_n, Mx_n)}(kt), S_{b(Ny_n, Ny_n, Ox_n)}(t), S_{b(Ly_n, Ly_n, Ny_n)}(t), S_{b(Mx_n, Mx_n, Ox_n)}(t)) \geq 0$$

that is,

$$\phi(S_{b(Ly_n, Ly_n, Mx_n)}(kt), S_{b(Mx_n, Mx_n, Ox_n)}(t), S_{b(Ly_n, Ly_n, Mx_n)}(t), S_{b(Mx_n, Mx_n, Ox_n)}(t)) \geq 0$$

As ϕ is nondecreasing in the first argument, we have

$$\phi(S_{b(Ly_n, Ly_n, Mx_n)}(t), S_{b(Mx_n, Mx_n, Ox_n)}(t), S_{b(Ly_n, Ly_n, Mx_n)}(t), S_{b(Mx_n, Mx_n, Ox_n)}(t)) \geq 0$$

Using (A), we get $S_{b(Ly_n, Ly_n, Mx_n)}(t) \geq S_{b(Mx_n, Mx_n, Ox_n)}(t)$.

Letting $n \rightarrow \infty, S_{b(w, w, z)}(t) \geq 1$ for all $t > 0$.

Hence $S_{b(w, w, z)}(t) = 1$

Thus $w = z$.

This shows that $Ly_n \rightarrow z$ as $n \rightarrow \infty$.

suppose that $N(X)$ is complete subspace of X .

Then $z = Nu$ for some $u \in X$.

Subsequently, we have $Ly_n \rightarrow Nu, Mx_n \rightarrow Nu, Ox_n \rightarrow Nu$ and $Ny_n \rightarrow Nu$ as $n \rightarrow \infty$.

By (3.12.4), we have

$$\phi(S_{b(Lu, Lu, Mx_n)}(kt), S_{b(Nu, Nu, Ox_n)}(t), S_{b(Lu, Lu, Nu)}(t), S_{b(Mx_n, Mx_n, Ox_n)}(t)) \geq 0$$

Letting $n \rightarrow \infty$

$$\phi(S_{b(Lu, Lu, Nu)}(kt), 1, S_{b(Lu, Lu, Nu)}(t), 1) \geq 0$$

As ϕ is nondecreasing in the first argument, we have

$$\phi(S_{b(Lu, Lu, Nu)}(t), 1, S_{b(Lu, Lu, Nu)}(t), 1) \geq 0$$

By using (A), we get $S_{b(Lu, Lu, Nu)}(t) \geq 1$ for all $t > 0$.

Hence, $S_{b(Lu, Lu, Nu)}(t) = 1$.

Thus, $Lu = Nu$.

The weak compatibility of L and N implies that $LNu = NLu$ then $LLu = LNu = NLu = NNu$.

On the other hand, since $L(X) \subseteq O(X)$, there exists a $v \in X$ such that $Lu = Ov$.

we show that $Ov = Mv$.

By (3.12.4), we have

$$\phi(S_{b(Lu, Lu, Mv)}(kt), S_{b(Nu, Nu, Ov)}(t), S_{b(Lu, Lu, Nu)}(t), S_{b(Mv, Mv, Ov)}(t)) \geq 0$$

that is ,

$$\phi(S_{b(Ov, Ov, Mv)}(kt), 1, 1, S_{b(Mv, Mv, Ov)}(t)) \geq 0$$

As ϕ is nondecreasing in the first argument, we have

$$\phi(S_{b(Ov, Ov, Mv)}(kt), 1, 1, S_{b(Mv, Mv, Ov)}(t)) \geq 0 \quad [\text{As } S_{b(x, x, y)}(t) = S_{b(y, y, x)}(t)]$$

Using (a), we get $S_{b(Ov, Ov, Mv)}(t) \geq 1$ for all $t > 0$.

Hence,

$$S_{b(Ov, Ov, Mv)}(t) = 1.$$

Thus, $Mv = Ov$.

This implies $Lu = Nu = Ov = Mv$. The weak compatibility of M and O implies that $MOv = OMv$ and then $OOv = OMv = MOv = MMv$.

Now, we will show that Lu is a common fixed point of L, M, N and O .

In view of (3.12.4) it follows

$$\phi(S_{b(LLu, LLu, Mv)}(kt), S_{b(NLu, SEu, Tv)}(t), S_{b(LLu, LLu, NLu)}(t), S_{b(Mv, Mv, Ov)}(t)) \geq 0$$

that is,

$$\phi(S_{b(LLu, LLu, Lu)}(kt), S_{b(LLu, LLu, Lu)}(t), 1, 1) \geq 0$$

As ϕ is nondecreasing in the first argument, we have

$$\phi(S_{b(LLu, LLu, Lu)}(t), S_{b(LLu, LLu, Lu)}(t), 1, 1) \geq 0$$

Using (B), we get $S_{b(LLu, LLu, Lu)}(t) \geq 1$ for all $t > 0$. Hence $S_{b(LLu, LLu, Lu)}(t) = 1$

Thus $LLu = Lu$.

Therefore, $Lu = LLu = NLu$ and Lu is a common fixed point of L and N . Similarly, we prove that Mv is a common fixed point of M and O . Since $Lu = Mv$, we conclude that Lu is a common fixed point of L, M, N and O . The proof is similar when $O(X)$ is assumed to be a complete subspace of X . The cases in which $L(X)$ or $M(X)$ is a complete subspace of X are similar to the cases in which $O(X)$ or $N(X)$ respectively, is complete since $L(X) \subseteq O(X)$, $M(X) \subseteq N(X)$.

$Lu = Mu = Ou = Nu = u$ and $Lv = Mv = Nv = Ov = v$ then (3.12.4) gives

$$\phi(S_{b(Lu, Lu, Mv)}(kt), S_{b(Nu, Nu, Ov)}(t), S_{b(Lu, Lu, Nu)}(t), S_{b(Mv, Mv, Ov)}(t)) \geq 0$$

that is ,

$$\phi(S_{b(u, u, v)}(kt), S_{b(u, u, v)}(t), 1, 1) \geq 0$$

sing (b), we get $S_{b(u, u, v)}(t) \geq 1$ for all $t > 0$.

Hence, $S_{b(u, u, v)}(t) = 1$.

Thus, $u = v$.

Therefore, the common fixed point is unique.

The following example illustrates our result.

Example 3.13. Let $(X, S_b, *, k)$ be an S_b -Menger space as defined in example (3.2)

Defined $L, M, N, O: X \rightarrow X$ by

$$\begin{aligned} L(x) &= \{2, & \text{when } x = 2 & 1, & \text{when } 2 < x < 20 \\ M(x) &= \{2, & \text{when } x = 2 & 7, & \text{when } 2 < x < 20 \end{aligned}$$

$$\begin{aligned}
 N(x) &= \begin{cases} 2 & \text{when } x = 2 \\ 6 & \text{when } 2 < x \leq 10 \\ (x-7) & \text{when } 10 < x < 20 \end{cases} \\
 O(x) &= \begin{cases} 2 & \text{when } x = 2 \\ 3 & \text{when } 2 < x \leq 10 \\ (x-3) & \text{when } 10 < x < 20 \end{cases}
 \end{aligned}$$

Then L, M, N and O satisfy all the conditions of theorem with $k \in (0, 1)$ and have a unique common fixed-point $x = 2$. Clearly (L, N) and (M, O) are weakly compatible since they commute at their coincidence points. Let sequence $\{x_n\}$ be defined as $x_n = 10 + \frac{1}{n}$, $n \geq 1$, then we have $M x_n = M x_n = 7$. Hence, M and O satisfy the property (E.A.).

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